This low-cost 6-digit frequency counter module uses readily available components and can measure up to 40MHz with a resolution of 1kHz. It is ideal for adding a digital frequency display to a function generator or to some other project.

A 6-Digit Frequency Counter Module

Most simple frequency counter designs are based on the 74C926 integrated counter chip. Unfortunately, this device is now quite expensive and can only handle four digits which means the resolution isn’t all that great. By contrast, this alternative design is much lower in cost and has six digits for improved display resolution.

As presented, the circuit features two signal inputs. The first of these is fed directly to the main counter circuit and this gives a direct readout in Hertz (Hz) up to a maximum of 99,999,999 Hz (i.e., just under 1 MHz).

The second input is fed to the counter circuit via an onboard divider circuit or prescaler. This prescaler divides the input frequency by 1000, which means that the display now shows the measured frequency in kHz. As a result, the circuit can now measure frequencies up to about 40 MHz.

Because the display reads directly in Hz or kHz, there is no need for decimal point switching and the associated complexity that this involves. There are no switches or controls — you simply feed the signal into the appropriate input for a direct readout in Hz or kHz.

How it works

Let’s now take a look at the circuit details — see Fig. 1. At the heart of the design are two 4553 triple BCD (binary coded decimal) counters (IC4 & IC5), which are wired in cascade fashion. Each of these ICs contains three synchronously cascaded BCD counters, three output latches and a 3-channel BCD output multiplexer with an internal oscillator. That’s quite a lot in one package and makes the 4553 ideal for a frequency counter application.

The basic principle behind the frequency counter is to count the number of input pulses that occur within a precise one-second window. The value stored in the counter chip will then equal the exact frequency in Hertz and this is then displayed on the 6-
Specifications

Frequency Readout: 6-digit 7-segment LED display.
Frequency Range: 1Hz-1MHz (1Hz resolution); 1kHz-40MHz (1kHz resolution). Can be easily modified for other ranges and resolutions.
Input Signal Level: 5V TTL/CMOS compatible.
Decimal Point Switching: Optional.
Size: 116mm x 35mm x 25mm x 30mm.
Supply Requirements: 5V DC @ 90mA.

Digital display. Let's take a look at how this works in detail.

IC2 is a 24-stage binary divider and oscillator. It divides the 4.194304MHz crystal (X1) frequency by 8,388,608 ($2^{22}$) at its Q23 output, to give a precise 0.5Hz clock signal. This signal then drives the DISABLE input (pin 11) of the first 4553 (IC5).

Let's initially assume that IC4 and IC5 have both been reset and that the DISABLE line has just gone high. This stops input pulses from clocking the counter and is the Latch/Display phase of the operation.

At the same time, the DISABLE signal is differentiated by a .001µF capacitor and 10kΩ resistor (to form a short positive-going pulse) and fed to IC3a. IC3a inverts this signal and the resulting negative-going pulse on its pin 3 output drives the latch enable (LE) pins of ICs 4 & 5. This latches the current counter value into the output registers and this is the value that's displayed on the 7-segment LED readouts.

Pin 3 of IC3a also drives a second differentiating circuit, again consisting of a .001µF capacitor and 10kΩ resistor. The resulting signal is then squared and buffered by IC3b and IC3c to provide a master reset (MR) pulse. This resets the counters in ICs 4 & 5, so that they are ready to start counting again.

After that, the DISABLE signal line subsequently goes low and the counters count the input pulses for precisely one second until the DISABLE line returns high again. This is the counting phase of the operation.

This Counting & Latch/Display sequence continues indefinitely while ever power is applied. As a result, the display is updated every two seconds with the current input frequency.

The OVF output (pin 14) of IC5 provides the means to cascade the second 4553 counter (IC4). It connects to the CLK input of IC4, so that we effectively have a 6-digit BCD counter.

IC5 has an internal free-running oscillator between pins 3 & 4. Its frequency is set by the .001µF capacitor between these two pins. Pin 3 also directly drives pin 4 of IC4 to keep it in sync and this also sets the multiplexing rate for the 7-segment displays.

As shown in Fig.1, the BCD outputs from ICs 4 & 5 (ie, at pins 5, 6, 7 & 9) each drive 4511 BCD-to-7-segment decoder/driver ICs (IC6 & IC7). These in turn each drive the a-g display segments of three displays. IC7 drives the segments of displays DISP1-DISP3, while IC6 drives the segments of DISP4-DISP6.

Note that the corresponding segments of DISP1-DISP3 are all connected in parallel. The same goes for the segments of DISP4-DISP6.

The DS1-bar, DS2-bar and DS3-bar lines from counter IC4 control the display multiplexing – ie, they control which displays are turned on at any given instant. When DS3-bar goes low, PNP transistor Q3 turns on and “sinks” the current for DISP1 and DISP4. Similarly, when DS2-bar goes low, transistor Q2 turns on and enables DISP2 & DISP5. And when DS1-bar is low, transistor Q1 switches on DISP3 & DISP6.

Prescaler circuit

IC1 and IC8, both dual 4-digit decade counters, form the divide-by-1000 prescaler circuit.

The first thing to note here is that the MR line also drives the CP1-bar input (pin 12) of IC1b. This may look puzzling at first glance because IC1b doesn’t appear to do anything. And that’s exactly what it does – nothing! This was just a convenient way to tie the CLK input on the PC board layout. After all, there’s no point adding extra links or tracks if you don’t have too.

It’s the three remaining 4-bit decade counters (IC1a, IC8a & IC8b) that do all the prescaling work, with each stage dividing by 10 to give an overall division of 1000. As shown in Fig.1, the input signal is fed to the CP0-bar (pin 1) input of IC1a and the divided output appears at the Q3 output (pin 7). This then drives the CP0-bar input of IC8a which in turn drives decade counter IC8b. Finally, IC8b drives the clock input (pin 12) of IC5.

The maximum frequency that can be displayed depends on the upper limit of the 74HC390 chips, which is around 40MHz. Note that this circuit will only accept TTL-level signals although signal-conditioning circuitry could be added to cater for other signal levels if required. The 4553 BCD counter chips will handle input frequencies up to about 1MHz.

The 7-segment LED displays are LT313 0.3-inch common-cathode types. Compatible types are the Agilent...
5082-7613 and the smaller HDSP7303/HDSP7803 units. These were used in favour of the more popular FND500 displays to simplify the PC board layout and to minimise the size.

The module requires a single +5VDC supply rail and this could come from any well-regulated source. The current consumption is around 90mA.

Possible modifications

The circuit can be easily modified to display any resolution and direct readout you require within its 40MHz capability. For example, let’s say that you wanted a direct readout in MHz with a display resolution of 100Hz – ie, the display must be capable of showing 99.9999MHz (if the circuit could handle frequencies that high).

This requires two things: a divide-by-100 prescaler and a decimal point between DISP4 and DISP5. The divide-by100 prescaler is easy – just bypass IC8b by connecting the pin 7 output of IC8a to the clock input (pin 12) of IC5. The decimal point is just as easy. All you have to do is connect a 470Ω resistor between pin 7 of DISP5 and the +5V rail.

So it’s quite easy to “customise” the display to your own requirements. If necessary, you could even add a switching arrangement so that you could easily select different ranges.

Construction

The design is built on two rectangular PC boards measuring 116 x 35mm. These are stacked together on 20mm spacers to form a single compact module.

The two boards are joined at both ends using straight wire links running directly from one to the other. Alternatively, flexible ribbon cable could be used to join the two boards and this could be left long enough so that the two boards could be easily separated at a later stage (eg, for modifications). Straight wire links are much neater, however.

Fig. 2 shows the assembly details for the two PC boards. Begin the assembly by installing the ICs and 7-segment LED displays on the display board, taking care to ensure that the displays are correctly orientated (ie, decimal point to bottom right). Don’t
A short length of insulated wire can be used to join the “Divider Output” to the “Freq Input” if the counter is to be used in divide-by-1000 mode.

Use sockets for the display board ICs – this would raise the ICs above the level of the displays and could lead to mounting problems later on.

The displays can be mounted in sockets to increase their height above the PC board if desired (e.g., you might want them to protrude through the front panel of an instrument case). Normally, however, the displays would be mounted directly on the PC board and would sit behind a Perspex window. Additional holes are provided in each PC board to make mounting easy.

Note that the prototype used two 470Ω DIL resistor packs which look just like (gold-coloured) ICs. Alternatively, you can fit individual 470Ω resistors here, as shown in Fig. 2.

You are now ready to build the logic board. Begin by fitting wire links to the locations shown, then fit PC stakes at the five points marked with a “star”. This done, you can fit the resistors and capacitors, crystal (X1) and the three transistors (Q1-Q3). The crystal should be a low-profile HC49/4H type to reduce its height.

You can now complete the logic board assembly by installing the six ICs. Make sure that each IC is in its correct location and is correctly orientated. The use of sockets is optional here – they were used on the prototype but you can save money by directly mounting the ICs on the PC board.

Once the board assemblies are complete, they can be stacked together on the 20mm spacers and secured using machine screws, nuts and washers. Finally, complete the assembly by installing the connecting links between the two boards. There are 13 links in all, seven at one end and six at the other.

Note that once the two boards are joined together, it can be difficult to access the top of the logic board for troubleshooting. For this reason, you might like to temporarily “patch” the two boards together using rainbow cable, so that they can be powered up and tested before the final assembly.

### Using the module

The module can be mounted on the front panel of your project by using another set of spacers or by gluing it in position. All external connections are made via the PC stakes on the logic board. Be careful when you connect the 5V DC power supply – there’s no reverse polarity protection, so if you get the leads the wrong way around, something’s bound to fry.

If you want the display to read in “Hz”, connect your input signal directly to the “Freq Input” terminal. This configuration can be used for signal frequencies up to 999,999Hz.

Alternatively, if you want the display to read in kHz, connect the input signal to the “Divider Input” terminal instead. You will also have to connect the “Divider Output” terminal to the “Freq Input” terminal using an insulated lead (see photo). As previously stated, this configuration allows measurements up to about 400MHz.

The frequency accuracy of the module will be dependant on the crystal used and the values of the two associated capacitors (22pF and 82pF). If necessary, these can be tweaked to “calibrate” the module. An accurate function generator or another frequency meter of known accuracy will be required for this task.

That’s all there is to it – your module should accurately indicate the input frequency and update the display every two seconds. Its application is limited only by your imagination. SC